

**Top Speakers:** 

Mathias Pillin, Bosch

Kai Lars Barbehön, BMW

Dr. Frank Kindermann, NIO

Igal Raichelgauz, Autobrains

Dominik Wee, Microsoft

Magnus Östberg, Mercedes-Benz

Vishnu Gurusamy Sundaram, Stellantis

Dr. Rolf Zöller, Porsche & Porsche Digital

Dr.-Ing. Yankin Tanurhan, Synopsys

The World's Largest Congress for Automotive Electronics, Software and **Applications!** 

**21st International Congress and Exhibition** October 18-19, 2023, Bonn, Germany

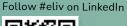
## **Main Topics:**

- Open Source Software
- Software Technologies
- E/E-Architecture
- Automotive Al
- Automated Driving
- Security
- Electronics Technology
- E-Vehicle Mobility
- System Engineering and **Processes**

## www.eliv-congress.com

## **Congress Highlights:**

- Automotive Trend Session: Open Source
- Panel Discussion: Transformation of **...** Working Environment
  - Parallel Conference E/E Commercial Vehicles
- Start-up Area and Special Start-up <u>الم</u> Program
- **Extensive Exhibition**
- Interactive Communication Points
- Meet with the Speakers
- Ä **Night of Electronics**



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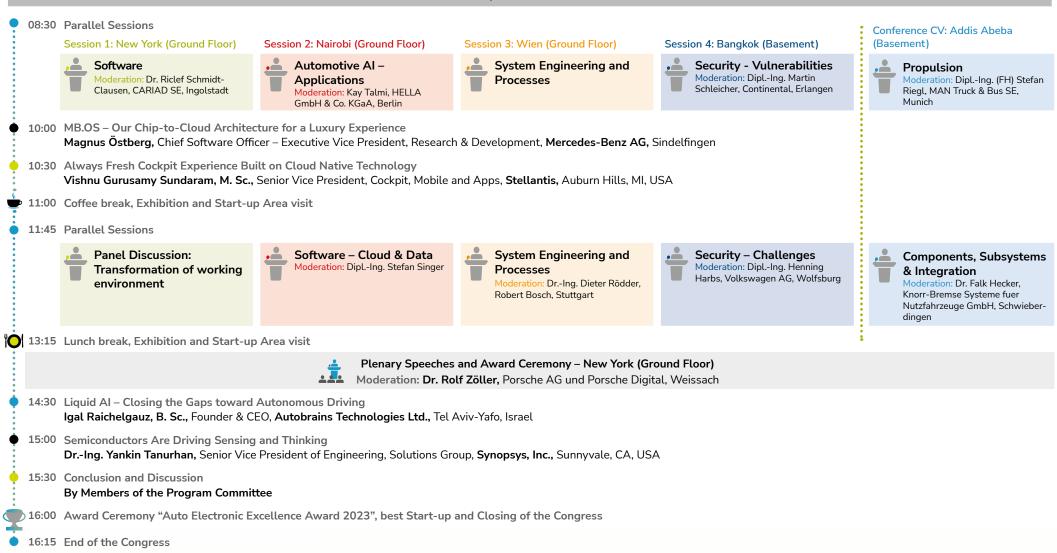
## **ELIV – Program Overview**

VDI

		Wed	<b>1st Congress Day</b> nesday, October 18, 2023			
07:45	7:45 Registration					
•			ry Speeches – New York (Ground Floor) olf Zöller, Porsche AG und Porsche Digita	l, Weissach		
•	08:45 Opening of the Congress, Current Market Situation & Hour of Topical Interest Dr. Rolf Zöller, Director E/E Smart Connected Vehicle Porsche AG and Managing Director Porsche Digital, Chairman of the Program Committee and Dr. Karl-Thomas Neumann, former CEO of Continental AG, Volkswagen China and Adam Opel GmbH, Founder & Owner					
09:10	Transforming the Future of Mobility Dominik Wee, Corporate Vice Preside		usiness Strategy & Development, <b>Micro</b>	soft Corporation, Munich		
09:40	NIO – Smart Electric Vehicles and Ba Dr. Frank Kindermann, Head of Batte	ttery Swapping ry System Europe, <b>NIO GmbH,</b> Munich			Parallel Conference:	
-	Dr. Frank Kindermann, Head of Battery System Europe, NIO GmbH, Munich         10:10       Re-Thinking E/E Architecture Design – A More Comprehensive Approach to Solve Future Challenges         DiplIng. Kai Lars Barbehön, Vice President Central Control Units, Wire Harness, Power Supply, BMW Group, Munich         10:40       Coffee break, Exhibition and Start-up Area visit					
10:40	Coffee break, Exhibition and Start-up	o Area visit			Comme	
11:25	Parallel Sessions				Conference CV: Addis Abeba	
	Session 1: New York (Ground Floor)	Session 2: Nairobi (Ground Floor)	Session 3: Wien (Ground Floor)	Session 4: Bangkok (Basement)	(Basement)	
• • • • •	Software – Open Source Moderation: DiplIng. Uwe Michael, mps, Rödermark	Automated Driving – Systems Moderation: Dr. Torsten Wey, Ford, Cologne	Electronics Technology Moderation: Ralf Lenninger, Former Continental, Regensburg	E-Vehicle Mobility – System Moderation: DrIng. Dieter Rödder, Robert Bosch, Stuttgart	Future of Transportation Moderation: Jörg Lützner, Continental Automotive GmbH, Schwalbach	
12:55	Lunch break, Exhibition and Start-up	Area visit				
14:25	Parallel Sessions					
0 0 0 0 0 0 0 0 0 0 0 0	Software – Automotive Trend Session – Open Source Moderation: DiplInf. Elmar Fricken- stein, Elstein Consulting & former BMW AG, Munich	Automated Driving – Sensors Moderation: Jürgen Bortolazzi, Porsche AG, Weissach	E-Vehicle architecture – Strategy Moderation: Dr. Jutta Schneider, Mercedes-Benz, Sindelfingen	E-Vehicle Mobility – Components Moderation: DiplIng. Christof Kellerwessel, former Ford, Cologne	Architecture & Software	
<b>1</b> 6:25	Coffee break, Exhibition and Start-up	o Area visit				
17:10	Parallel Sessions					
- - - - - - - - - - - - - - - - - - -	Software Moderation: Kai-Uwe Balszuweit, BMW Group, Munich	Automotive AI – Innovations Moderation: Joachim Langenwalter, Autobrains AI Technologies, Berlin	E-Vehicle architecture – Aspects Moderation: DiplIng. Stefan Teuchert, MAN Truck & Bus, Munich	Connectivity Moderation: DrIng. Michael Winkler, HELLA Fahrzeug- komponenten, Bremen	Autonomous Driving	
18:40	End of the first Congress Day				•	
•	Night of Electronics at the MS Rhein	Energie				
	5	5	v experts and use your chance to netwo	ork.		



### **2nd Congress Day** Thursday, October 19, 2023



## **1st Congress Day**

### Wednesday, October 18, 2023

#### 07:45 Registration

Plenary Speeches – New York (Ground Floor)

• Moderation: Dr. Rolf Zöller, Porsche AG und Porsche Digital, Weissach

- 08:45 Opening of the Congress, Current Market Situation & Hour of Topical Interest
  - Dr. Rolf Zöller, Director E/E Smart Connected Vehicle Porsche AG and Managing Director Porsche Digital, Chairman of the Program Committee and Dr. Karl-Thomas Neumann, former CEO of Continental AG, Volkswagen China and Adam Opel GmbH, Founder & Owner
- 09:10 Transforming the Future of Mobility with the Power of AI and the Cloud
  - Unlocking new business models, increasing efficiencies, creating new monetization opportunities using the power of AI and cloud computing
  - Accelerating innovation in the software-defined and autonomous vehicle space
  - Opening up new opportunities with the industrial metaverse
  - Dominik Wee, Corporate Vice President Manufacturing & Mobility, Sales, Business Strategy & Development, Microsoft Corporation, Munich
- 09:40 NIO Smart Electric Vehicles and Battery Swapping Smart EVs: next generation of BEV
  - Battery Swapping: fully recharged within less than 5 minutes
  - User Centric: aiming for the highest User satisfaction
  - Driven by Design: a premium car
  - Dr. Frank Kindermann, Head of Battery System Europe, NIO GmbH, Munich
- 10:10 Re-Thinking E/E Architecture Design A More Comprehensive Approach to Solve Future Challenges
  - Automotive E/E architectures are significantly shaped by the top trends of digitalization
  - Today's prevailing domain oriented E/E architectures result in hardly manageable functional interdependencies
  - Zonal physical electrical power system architectures in combination with high-performance integration platforms will lead into the future
  - Why and how BMW derives the central E/E infrastructure for the BMW NEW CLASS from a new, holistic E/E architecture approach
  - Dipl.-Ing. Kaj Lars Barbehön. Vice President Central Control Units. Wire Harness. Power Supply, BMW Group, Munich
- 10:40 Coffee break. Exhibition and Start-up Area visit

## ELIV – The App

### Simply download the Event-App and register!

The App will be available for download at the Apple App Store and the Google Play Store for all participants as of October.

#### App areas:

- · Digital congress program: create your own agenda at once
- General event information
- Evaluation and guestion function
- Exhibition information
- Service information

- Networking:
- Digital Business Card: create your Digital Business Card.
  - Share your data quickly and easily with other participants and save new contacts directly
    - Use the "Offer" and "Search" function to find and contact other participants
    - · Meeting Arrangement: request appointments with other participants

## Sponsor





#### Conference CV: Addis Abeba Wien (Ground Floor) (Basement) Nairobi (Ground Floor) Bangkok (Basement) New York (Ground Floor) • Software – Open Source Automated Driving -**Electronics Technology** E Vehicle Mobility – System Future of Transportation Moderation: Dipl.-Ing. Uwe Michael, Moderation: Ralf Lenninger, Former Moderation: Dr.-Ing. Dieter Rödder, Moderation: Jörg Lützner, Systems Robert Bosch, Stuttgart Continental Automotive GmbH. mps. Rödermark Continental, Regensburg Moderation: Dr. Torsten Wey, Ford, Schwalbach Cologne 11:25 11:25 **Criticality Driven Data Acquisition** Estimation of Body Height, Weight, A Holistic Approach for Designing Welcome to the Era of Logistics -Why Open Source – A New in Autonomous Driving - A Basis for and Gender of Vehicle Occupants a Battery Electric Vehicle Thermal Insights into Trends That Will Shape **Generation Perspective Completeness and Safety Argumen-**Using Machine Learning Management System the Future Patrick Böder, Senior Software tation Deep Learning Virtual testing of entire vehicle in a · Megatrends shaping the needs of Engineer and Open Source, Porsche Vehicle Occupant Monitoring Method developed in VVMethods single simulation environment societies and industries and the Digital, Ludwigsburg Basis for ISO21448 SOTIF validation Feature Estimation Explore design space to refine comsupply chains that serve them Efficient data acquisition in Patrick Laufer, M. Sc., Developponent and system requirements Navigating the future: The DHL 11:35 Develop an electrothermal model automated driving ment Engineer, Vehicle Safety, IAV Logistics Trends Radar - what it is, The Open Road Runs on Open • Smart Data analytics in automated Fahrzeugsicherheit GmbH & Co. KG, of battery pack capturing individual why it matters and how it supports Source driving Munich cell behavior innovation Vision of software-defined vehicle re-Dipl.-Ing. (FH) Max Nestoriuc, Team- Assess impact of powertrain and The DHL customer-centric innovatiguires accelerated pace of innovation leader ADAS Systemdesign & Validacooling system designs on overall on approach and ecosystem Open source has been a driver of tion, Co-authors: Himanshu Walia, performance Use case examples, ideas for innoinnovation in multiple industries M. Sc., both of AVL Deutschland Steve Miller, M. Sc., Product Manager vation and implementation levera- Key success factors include open GmbH, Stuttgart, Dipl.-Ing. Thomas Simscape Product Family, Technical ging technology as well as business collaboration with ecosystem. Guntschnig, AVL List Gmbh, Graz, Marketing, Co-author: Lorenzo Nico-& social trends a cloud-native and consistent letti, M. Sc., both of The MathWorks Dr. Klaus Dohrmann, Vice President, Austria platform and a functional safety GmbH. Munich Head of Innovation & Trend Research. certified base laver infrastructure DHL, Troisdorf Practicable solution must cover these success factors over entire vehicle life cycle (design to testing/ manufacturing to upgrades and maintenance) Francis Chow. VP & GM. In-vehicle Operating System and Edge, Red Hat, Inc., Sunnyvale, CA, USA 11:55 AUTOSAR Software Architecture -Vehicle-to-Vehicle (V2V) Commu-Active Noise Control: Helping Safe and Efficient Regenerative UNICARagil - Rethinking Archi-A Cornerstone for Software Defined nication as Enabler for Improved **Carmakers Design Better Cars** Braking Strategies for Heavy BEVs tectures for Fully Automated and Overview of Road Noise Control Regenerative braking of heavy **Driverless Vehicles** Vehicles and the Future of Mobility **Automated Driving Functions** Strategic Vision Connection to EU-funded project technoloav articulated vehicles Automated Driving Cooperations with other consortia • Description of the enabler Vehicle Design Compromises-cost, Model based brake force limitation E/E Architecture Vehicle API approach Description of use case and its test mass, complexity, ride quality, noise Wheel Slip Control Service Oriented Software Archi-Dr.-Ing. Peter Redlich, EU Chief and verification quality Leon Henderson, PhD, Function tecture Architecture & Software, Product Markus Kremer, System Architect Analysis of selected mechanical Developer, Vehicle Motion Manage- Technical Supervision and Cloud Development, Ford Werke GmbH, ADAS/AD, FEV.io GmbH, Aachen ment, Co-authors: Daniel Möller, versus electronic noise control Connectivity Cologne and Dr. Eduard Metzker. problems Maliheh Sadeghi Kati, all of Volvo Timo Woopen, M. Sc., Manager, Manager for strategic technical Summary of RNC advantages for GTT, Gothenburg, Sweden Research Area Vehicle Intelligence & cooperations, Products Embedded carmakers Automated Driving, Co-authors: Software. Vector Informatik GmbH. Dr. John Feng, Head of Active Sound Raphael van Kempen, M. Sc., Univ.-Prof. Dr.-Ing. Lutz Eckstein, all Stuttgart Management, Automotive Division,

Bose Corporation, Framingham, MA,

USA

of RWTH Aachen University

## **1st Congress Day**

#### 12:25 12:15

#### **Accelerating Software Defined** Vehicles through Open Source Software

- · Advantages of open source software for software-defined vehicles
- Overview of Automotive Grade Linux, an open source platform supported by 150+ members
- Production use cases for open source infotainment

Dan Cauchy, Executive Director of Automotive Grade Linux. The Linux Foundation, San Francisco, CA, USA

#### 12:35

Overview funding projects in the context of Automotive Open Source Prof. Dr.-Ing. Habil. Alois Knoll, Chair of Robotic, Artificial Intelligence and Embedded Systems. Technical University of Munich

12:55 Lunch break, Exhibition and Start-up Area visit

, Software – Automotive Automated Driving -Trend Session – Open Source Sensors Moderation: Dipl.-Inf. Elmar Fricken-Moderation: Jürgen Bortolazzi,

#### BMW AG, Munich 14:25 Building an Open-Source Ecosystem for Software-defined Vehicles -

stein, Elstein Consulting & former

### The Good, The Bad, and the Ugly

- Perspective on Software-defined Vehicle from a non-automotive company
- Current state of Open Source Software
- Challenges of building an Open Source Ecosystem
- Eclipse Software-defined Vehicle: **Overview & Current Status**
- Success factors from a Microsoft perspective
- Boris Engel, Program Director Automotive, Microsoft Corporation, Munich

#### Technological Innovations Enabling the Scalable Deployment of Autonomous Driving for Heavy Trucks

- How autonomy will transform the trucking industry
- Market opportunity for highly automated driving (HAD) products
- Plus's case study of building and commercializing high-performance modular autonomous driving software solutions that are affordable
- and scalable across vehicle types and applications Plus's state-of-art data-driven system for continuous learning with minimal human intervention Anurag Ganguli, PhD, Vice President
- of R&D, Plus, Santa Clara, CA, USA

Porsche AG, Weissach

· Combining vision and radar in

for high compute efficiency

highest point cloud density

Showcase pedestrian and bicycle

detection in real traffic situations

Systems and Software, Co-author: Dr.

Zorawar Bassi, both of indie Semicon-

Dr. Peter Gulden, SVP of Radar

ductor, San Jose, CA, USA

pedestrians

Using Radar + Vision Fusion for Impro-

difficult situations to securely detect

Overall architecture and distribution

between edge and central compute

ved Low-light Pedestrian Detection

#### New Opportunities with Software-Defined Lighting -Personalization and Emotionalization of Vehicle

- Software Defined Lighting
- Established signal functions in a new appearance
- Experience the vehicle by light
- EE architecture for Software Defined Liahtina

Dr. Carsten Wilks, Head of Innovation Lighting Electronics, Co-authors: Dr. J. Roslak, both of Hella KGaA Hueck & Co., Lippstadt

#### A Cloud-based Self-Learning Digital Twin Solution for Increasingly Accurate Range Prediction in **Battery Electric Vehicles**

- Data-driven function development
- Framework for self-learning data-driven digital twin model
- Load profile prediction based on destination forecast, vehicle resistance information and speed profile prediction

Dr.-Ing. Marius Wegener, Team Leader Controls, E-Mobility Systems, Co-authors: Dr.-Ing., Rene, Savelsberg, both of FEV Europe GmbH, Aachen, Lukas Schäfers, M. Sc., **RWTH Aachen University** 

#### Bulli, Pick Me Up: Continuous Testing as a Key for Developing a Robot-Taxi-System

- Autonomous vehicles. MaaS. TaaS. robot cab
- Continuous Integration/Continuous Deployment
- Software Integration
- Testing & simulation of automated vehicles

Dr.-Ing. Christian Rösener, Head of Integration & Verification, Autonomous Driving, MaaS, TaaS, Volkswagen AG, Wolfsburg

### Vehicle Architecture -Strategy

Moderation: Dr. Jutta Schneider, Mercedes-Benz, Sindelfingen

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#### Scalable Plug & Play High-Performance Computer and Fluid Cooling Solutions

- Flexible and scalable High-Performance Computer concept for any vehicle architectures
- Innovative "plug & play" fluid cooling solution for zero gap heat Using multi-static radar operation for transfer
  - · Flexible cooling pad allows a maximum of flexibility for OEMs Dipl.-Ing. Andreas Heise. Head of ADCU Technology, Principal Expert Mechatrlvoonic Technologies, Continental AG. Eschborn

#### E Vehicle Mobility -Components Moderation: Dipl.-Ing. Christof Kellerwessel, Former Ford, Cologne

#### How to Improve EV Battery Cell Quality

- Identify key challenges and industry trends for battery cell production.
- Learn about cutting edge test and inspection techniques (EIS, ACIR, scientific machine learning).
- Get insights to optimize cell testing during production to improve yield, quality, and throughput.
- Hear about today's industry use cases such as the Battery Innovation Center

Davide Cotterle, Senior Application Engineer, Transportation Business Unit, NI (National Instruments), Munich

### Architecture & Software

#### SAE J1939 in AUTOSAR - CAN FD and CAN XL

- Realizing J1939-22 in AUTOSAR
- Higher transmission rates with CAN FD (J1939-22)
- Usage of the Multi-PG concept

 Outlook on J1939 with CAN XL Timo Schwendner, Solution Manager J1939, Productline Embedded Software and Systems, Co-author: Martin Schlodder, both of Vector Informatik GmbH. Stuttgart



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14:55	<ul> <li>14:45</li> <li>Eclipse SDV: Chances and Challenges of Collaboration in the Open</li> <li>Collaboration on implementation</li> <li>The advantages of Open Source in the automotive industry</li> <li>Jointly building a platform with scale</li> <li>How Open Source can help to attract developers</li> <li>Michael Plagge, Vice President Ecosystem Development, Eclipse Foundation AISBL, Brussels, Belgium</li> <li>15:05</li> <li>Robert Day, Director, Autonomous Vehicles, Arm, San José, CA, USA</li> </ul>	Automotive Radar Technology Inno- vations Power Next-gen ADAS and Autonomous Driving 28nm RFCMOS single-chip Radar integration High-resolution 4D Imaging Radar technology Next-generation vehicle architectu- res – enabling new Radar capabi- lities Matthias Feulner, Senior Director Marketing, ADAS, NXP Semiconduc- tors Germany GmbH, Munich	Strategically Migrating, Mapping and Scaling Software to New SoC, Domain & Zone Architectures and HPC • Timing, Performance and Event Chains • Mapping & software to new hardware • Exploring architecture variants Dr. Ralf Münzenberger, CEO, Co-author: Olaf Schmidt, both of INCHRON AG, Erlangen	Analysis of WBG Based Hybrid Semiconductors Approach for Bidirectional PFC in On-Board Charger Applications • On board charger • Wide band gap devices • PFC • Car electrification DrIng. Domenico Nardo, Power Specialist for automotive applications, Technical Marketing, Co-authors: Francesco Gennaro, Giuseppe Aiello, all of STMicroelectronics GmbH, Aschheim	<ul> <li>Event-Chain-Focused Development of System Architectures Makes</li> <li>Complex Systems Manageable</li> <li>End-to-end validation of real-time requirements in vehicle systems</li> <li>Event chain analysis for higher-level timing requirements</li> <li>Early error detection improves project planning security</li> <li>Development productivity can be significantly increased</li> <li>DiplIng. Ferry Kraft, Function Ar- chitect, R&amp;D Electric/Electronic, MAN Truck &amp; Bus SE, Munich and DiplIng.</li> <li>Florian Mayer, Project Manager, Professional Services, Co-authors: Jan Apelt, DrIng. Ralf Münzenberger, all of INCHRON AG, Erlangen, Christian Winkler, MAN Truck &amp; Bus SE, Munich</li> </ul>
15:25	An OEM Perspective of Open Source – Slot Reserved for BMW	Combining SD Maps and ADAS Perception for Advanced Augmen- ted Reality Guidance • Overall In-car Augmented Reality Architecture • Using Navigation and ADAS Perception input for Augmented Reality • Situation Analysis • 3D Scene Creation Dr. Martin Pfeifle, CTO, NNG Kft., Budapest, Hungary, Co-authors: Prof. DrIng. Niclas Zeller, Hochschule Karlsruhe, Dr. Andreas vom Felde, StradVision, Munich	<ul> <li>Towards the Next Step in Vehicle E/E Architectures</li> <li>Path towards future software-de- fined vehicle E/E architectures</li> <li>Technology enablers such as cross-domain integration platforms</li> <li>Focus on cost-efficient and salable solutions shaping future E/E designs</li> <li>Dr. Thorsten Huck, Vice President Competence Center E/E Architectures, Co-author: Dr. Andreas Achtzehn, both of Robert Bosch GmbH, Abstatt</li> </ul>	Power Electronic System Technology for Future High-Power Charging Systems on Highways or Large Inner-City Electric Charging Stations with Several MVA System Size • System Topology • Power Electronics • Design • Measurement Results DiplIng. Andreas Hensel, Head of Group, Power Electronics and Grids, Co-author: DiplIng. David Derix, both of Fraunhofer ISE, Freiburg	<ul> <li>How Data-Driven Approaches Enhance Agile and Quality-Assured Software Development for Automa- ted Driving</li> <li>Data collection and management</li> <li>Data virtualization for digital twin creation</li> <li>Different Use-Cases for Data-Driven Software Development</li> <li>Processes/Methods/Tools Enabling Agile and Quality-Assured Software Development</li> <li>DiplIng. Klaus Fuchs, Senior Product Manager, ADAS/AD, AVL Software and Functions GmbH, Regensburg and DiplIng. Gernot Hasenbichler, Senior Product Mana- ger, ADAS/AD, AVL List GmbH, Graz, Austria</li> </ul>

## **1st Congress Day**

#### 15:55 15:45

Panel Discussion on "Open source"

Moderation: Elmar Frickenstein, Elstein Consulting & former BMW AG

#### Panelist:

Francis Chow, Red Hat Michael Plagge, Eclipse Boris Engel, Microsoft Robert Day, Arm BMW



#### **Development and Testing Autono**mous Vehicles (AV) at Scale

- Data at scale for hybrid cloud infrastructures for smart AD data logging and processing
- Linear scalability of performance with optimized costs
- Lower cost of infrastructure from edge to cloud, by avoiding the need to store the data across multiple locations
  - Based on open source and secure standards to maintain a single source of truth
- · Data management and data orchestration. scalable based on the containerized applications Dipl.-Ing. Frank Kraemer, System Architect, Technical Presales, IBM, Frankfurt am Main

#### Mastering Complexity in Modern Vehicle Software Updates

- Software dependency model as interface between engineering and after sales
- Unifying over-the-air-updates and workshop operations
- Tracing software updates for UN-ECE SUMS
- Detecting and handling invalid vehicle states

Dr. rer. nat. Oliver Meyer, Head of Department, System Development Lifecycle Management & After Sales, Co-author: Dr. rer. nat. Boris Böhlen, both of DSA Daten- und Systemtechnik GmbH. Aachen

#### Multi-Level GaN Inverter - Development of HV Solutions for Highest EV Performance and Efficiency

- Benefits include higher voltages, reduced harmonic losses. and improved NVH characteristics and FMC behavior
- GaN components show additional superior influence on systems over traditional silicon applications
- New ways to improve e-motor efficiency and reduce losses in the WLTP drive cycle by 25 %

Lukasz Roslaniec, PhD, Department Leader & Engineer, Power Electronics, Co-author: Thomas Hackl. both of hofer powertrain, Nürtingen

#### Usage of UDS Service 0x29

- UDS service 0x29 (Authentication
- Service) Library

Munich

- scalable solutions
- secure gateway

Lothar Zizala, Vehicle Security & Safety, MAN Truck & Bus SE, Munich and Ralf Ramrath, iQmine GmbH,

#### 16:25 Coffee break, Exhibition and Start-up Area visit



#### 17:10 What It Really Takes to Empower Software Defined Vehicles

- The industry's journey to bring truly software defined vehicles at scale to the roads
- Key levers: decoupling hardware and software at decisive points in the vehicle architecture, data-driven development and operations, scalable service architectures
- Tangible contributions a software-driven Tier1 can bring to the industrv

Technology, Gerlingen

## Dr. Mathias Pillin. Member of the Business Sector Board Bosch Mobility Solutions. Head of Mobility

#### • Automotive AI -Innovations

Moderation: Joachim Langenwalter, Autobrains AI Technologies, Berlin

#### How to Become a Leader By Development of AI: ChatGPT Research Papers Analyzed

- Al can facilitate fascinating things. The development methodology from ChatGPT reveals important learnings about successful AI development
- These learnings can be well transferred to automotive use cases
- · If the learnings are followed, automotive can be successful with AI Dr. Ulrich Bodenhausen, Manager Consulting, Product Group Consulting, Vector Consulting Services GmbH. Stuttgart

#### Vehicle Architecture -Aspects

Moderation: Dipl.-Ing. Stefan Teuchert, MAN Truck & Bus, Munich

#### **Continuous System Architecture Development for Automated Driving** Features

 Agile development processes and methods applied to Model-based Systems Engineering

,

- Continuous, parallelized system architecture development with SvsML and CI/CD
- Toolchain to automate model quality assurance, configuration and integration

Anuj Malvankar, M. Sc., Team Leader, Systems Engineering Processes, Co-authors: Stephan Riediger, Vijay Konenki, all of FEV.io GmbH. Aachen

#### Connectivity

Moderation: Dr.-Ing. Michael Winkler. HELLA Fahrzeugkomponenten. Bremen

#### Achieving Ubiguitous Connectivity for Future Vehicles

- In-vehicle 5G mmWAVE helps to solve the capacity issue for V2N & V2X
- Non-terrestrial-networks (NTN) complement the cellular terrestrial-networks (TN) to close the existing coverage gap, starting with 5G Rel. 17. further enhancements in 5G advanced and towards 6G
- The digital in-vehicle connectivity architecture supports the integration of 5G mmWAVE and e.g. Satellite **Broadband Communication**

Dipl.-Ing. Thomas Hinzmann, Lead Technologist, Strategy & Innovation, Connected Mobility Solutions, Co-author: Dipl.-Ing. Dietmar Schnepp, both of Molex CVS Bochum GmbH. Bochum

#### **,** Autonomous Driving

#### Unlocking the Power of Automated Driving Technology Today

- How autonomy will transform the trucking industry
- Market opportunity for highly automated driving (HAD) products
- Plus's unique approach to empowering driver-in and fully autonomous solutions via Open Autonomy Platform
- Plus's case study of building and commercializing high-performance modular autonomous driving software solutions that are affordable and scalable across vehicle types and applications

Sun-Mi Choi, MBA, VP of Business Development, Plus, Santa Clara, CA, USA



<ul> <li>Digital transformation of autom driven by electrification, autonom</li> <li>Changing vehicle architectures a cars become increasingly soft- ware-defined</li> <li>Smart, connected cars of the fut require new digital technology l cloud connected services, advar ced driver assistance systems, a customized in-vehicle infotainm</li> <li>AI and wireless technologies wi support evolving transportation trends</li> <li>Enrico Salvatori, SVP &amp; Presiden Europe/MEA, Qualcomm, Munich</li> </ul>	<ul> <li>Passive Audio</li> <li>Using passive sound field to extend ADAS capability         <ul> <li>Overcoming challenges with AI</li> <li>Practical system architecture on limited automotive MCUs</li> <li>Performance in live testing</li> <li>Jeffrey Sieracki, PhD, Director of AI</li> <li>Engineering, AloT Center of Excel- lence, Co-authors: Rui Yang, Matthew Caggiano, all of Renesas Electronics, Columbia, MD, USA</li> </ul> </li> </ul>	<ul> <li>Challenges and Tasks of the Centralized and Service Oriented End-to-End EE Architecture</li> <li>STLA Brain: a new Stellantis Tech new platform</li> <li>Collaboration model strategies with new Stellantis partnerships</li> <li>Leandro Lara, Vice President, HW</li> <li>Engineering &amp; EE Architecture</li> <li>Stellantis, Paris, France</li> </ul>	<ul> <li>Radar detection range extension via V2X</li> <li>Cooperative blind spot detection</li> <li>Non-line-of-sight perception</li> <li>Dr. rer. nat. Patrick Friedel, Advanced Engineering Program Manager, Advanced Engineering Electronics, Co-authors: Shan Danfeng, Kamill Eliasch, all of HELLA GmbH &amp; Co. KGaA, Lippstadt/Nanjing, China</li> </ul>	<ul> <li>Safe Autonomous driving</li> <li>Daimler Truck dual partnership strategy</li> <li>Development Strategy Torc Robotics for Autonomous Trucks</li> <li>Challenge of releasing an autono- mous truck</li> <li>PhD Axel Gern, Managing Director, Development, Torc Europe GmbH, Stuttgart</li> </ul>
<ul> <li>18:10 Maintaining Open-Source Based Software or What Is the True Co of Free?</li> <li>Regulations like UNECE R 156 a ISO/SAE 21434 mandating long periods of fixes and updates</li> <li>Need for car manufacturers to ta a proactive approach to softwar maintenance and support</li> <li>Problems and possible solution associated with open-source components and platforms in th automotive industry</li> <li>Dr. Joachim Schlosser, Senior Ma ger, Strategic Consulting, Co-auth Jens Petersohn, both of Elektrobit Automotive GmbH, Munich</li> <li>18:40 End of the 1st Congress Day</li> </ul>	<ul> <li>30%?</li> <li>Enabling root cause analysis for integration validation</li> <li>Identification of high probability testing focus</li> <li>Enabling continuous and seamless OTA updates at 10% of the cost</li> <li>Evidence of effects to regulated systems from software updates in accordance with UNECE WP.29 (R156)</li> <li>Pre-error detection of software</li> </ul>	<ul> <li>New E/E Architecture</li> <li>Current situation and challenges of the E/E Architecture</li> <li>Trends in the E/E Architecture</li> <li>DiplInform. Yves Duhr, Central E/E Architect, MB.OS Architecture, Mercedes-Benz AG, Sindelfingen</li> </ul>	<ul> <li>A Holistic Approach for a Universal Vehicle-to-Automotive-Service- Robot Communication Interface</li> <li>Introduction into the field of Auto- motive Service Robots (ASR)</li> <li>Trade-Off of modern R2X and V2X communication interfaces</li> <li>Requirements and resulting adapta- tions for V2ASR communication for a specific ASR use case</li> <li>Detailed explanation of a universal vehicle communication interface (UVCI) model</li> <li>Lukas Heinrich, M. Sc., Industrial PhD Candidate, Robotics, Group Innovati- on, Co-authors: Malte Springer, M. Sc., both of Volkswagen AG, Wolfsburg, Prof. Dr. Jürgen Pannek, TU Braun- schweig</li> </ul>	<ul> <li>Key Factors of a robust and safe Automated Driving Function – Transferable Insights of City-Bus Platooning in Munich</li> <li>System performance – Required upgrade of the electronic architecture</li> <li>Redundancy for operational reliabi- lity and safety</li> <li>Methods for a well-structured evelopment and test phase</li> <li>Application example: Analysing the platooning of EBUSCO 3.0 12m city-buses</li> <li>Nicole Kechler, M. Sc., Member of Scientific Staff, R&amp;D, Karlsruhe Insti- tute of Technology (KIT), Co-authors: Niranjana Venkatesh, M. Sc., Ebusco, Deurne, The Netherlands, Prof. Dr Ing. Eric Sax, Institut fuer Technik der Informationsverarbeitung (ITIV) – Karlsruhe Institute of Technology (KIT)</li> </ul>

The VDI invites all participants, speakers, sponsors and exhibitors to join the "Night of Electronics" aboard Europe's largest event liner, the MS Rheinenergie. This evening reception is the perfect opportunity to network and continue the discussions of the first congress day in a relaxed atmosphere. Meet your peers and business partners and enjoy a varied entertainment program.

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## 2nd Congress Day

Thursday, October 19, 2023				
New York (Ground Floor)	Nairobi (Ground Floor)	Wien (Ground Floor)	Bangkok (Basement)	Conference CV: Addis Abeba (Basement)
Software Moderation: Dr. Riclef Schmidt- Clausen, CARIAD SE, Ingolstadt	Automotive AI – Applications Moderation: Kay Talmi, HELLA GmbH & Co. KGaA, Berlin	System Engineering and Processes	Security – Vulnerabilities Moderation: DiplIng. Martin Schleicher, Continental, Erlangen	Propulsion Moderation: DiplIng. (FH) Stefan Riegl, MAN Truck & Bus SE, Munich
<ul> <li>08:30 Transcending Physical Time – Accurate Simulation of Novel HW/ SW-Decoupled Systems</li> <li>Despite all attempts to create hard- ware abstraction layers, automotive software is often tightly coupled to HW timing behavior</li> <li>Next generation middleware can help do decouple timing dependen- cies from functional code</li> <li>We get more robust code with higher portability across HW generations and vendors</li> <li>We can build highly accurate test feedback loops without perfect HW simulators</li> <li>Christian Uebber, CTO, Engineering, ETAS GmbH, Stuttgart, Co-authors: Dr. Karsten Muehlmann, DrIng. Phi- lipp Mundhenk, both of Robert Bosch GmbH, Stuttgart</li> </ul>	<ul> <li>Al-Based Energy Management of Next Generation Architectures</li> <li>New power distribution concept in the upcoming Server-Zone E/E architecture</li> <li>Investigation in different Electrical and Electronic (E/E) structures, and evaluate their advantages, features, and potentials</li> <li>Division of responsibilities between the server and different zones improved using machine learning or artificial intelligence</li> <li>DiplIng. Martin Schlecker, Head of Department, Vehicle Control Unit, Co-authors: Thomas Zipper, Dr. Lin Li, all of AVL Software and Functions GmbH, Regensburg</li> </ul>	<ul> <li>Virtual Homologation (UNECE R 155/156/157) – New Opportuni- ties for the Automotive Industry to Enable More Efficient Development Processes and Improving Safety and Quality of Vehicles for High Scaling Software Updates Based on Current and Future Regulations</li> <li>Number of homologation relevant software updates will explode in near future</li> <li>New approaches for homologation/ type approval are required in order to fulfill customer expectations and in compliance with legal authorities and OEMs product roadmaps</li> <li>Partnerships between legal authori- ties, certifiers, OEMs and technology companies</li> <li>DiplIng. Robert Lokner, MBA, Direc- tor Automotive, Automotive Industry, Microsoft Corporation, Munich and DiplIng. Alexander Kraus, CTO, Mobility Division, TÜV SÜD Auto Service GmbH, Munich</li> </ul>	<ul> <li>Automotive Software Vulnerabilities: Strategies for Early Detection, Mitigation, and Prevention in the Software-Development-Lifecycle</li> <li>Root causes of automotive software vulnerabilities</li> <li>Most common weakness classes of automotive software vulnerabilities</li> <li>Testing methodologies for detecting vulnerabilities</li> <li>Preventing most vulnerabilities during development</li> <li>DrIng. Andreas Weichslgartner, Senior Technical Security Engineer, Architecture, Security &amp; Technologies, CARIAD SE, Nuremberg</li> </ul>	<ul> <li>Hydrogen – A Game Changer in the Automotive Industry and Beyond</li> <li>H2 market and potentials</li> <li>The road to net zero: H2 as preferred solution?</li> <li>Bosch's Contribution in mobile applications</li> <li>and beyond (stationary applications)</li> <li>Dr. Silke Spitzer, Senior Vice President SW Engineering Powertrain Solutions – Electronic Controls, Robert Bosch GmbH, Plochingen</li> </ul>
<ul> <li>09:00 A Unified Middleware for SoC- Agnostic Application Development         <ul> <li>Production-ready middleware based on open source</li> <li>Unified application framework for microcontrollers, microprocessors and hardware accelerators</li> <li>Relocation of applications with minimum effort</li> <li>DiplIng. (FH) Stefan Duda, Vice President Product, Co-author: Laurent Emmerich, both of Apex.Al GmbH, Munich</li> </ul> </li> </ul>	<ul> <li>Generative AI – How AI Models</li> <li>Change the Way We Develop</li> <li>Automotive Products</li> <li>Generative AI can help us develop better products and is a key enabler for self-supervised learning</li> <li>From design and prototyping to quality control and user experience</li> <li>Optimization of products, material usage and final performance</li> <li>DrIng. Pia Dreiseitel, Growth Field Manager AI Technologies, Research and Advanced Engineering, Co-author: Dr. Dilara Yesilbas, both of Continen- tal Automotive Technologies GmbH, Frankfurt am Main/Regensburg</li> </ul>	<ul> <li>An Approach to Digital Lifecycle Management as a Service</li> <li>New customer experience by mo- difying the automotive ecosystem</li> <li>Strategic development and control of software updates for new user experiences in automotive industry</li> <li>Software updates as a new appro- ach to create customer value</li> <li>DiplInf. Henry Bastian, Product Ma- nager DLCM Control Center, Digital Lifecycle Management, Co-authors: DiplIng. Benjamin Baron, Dr. Frank Althoff, all of CARIAD SE, Wolfsburg</li> </ul>	<ul> <li>New Standards and Best Practices to Mitigate Supply Chain Security Risks of Software-Driven Products</li> <li>Insights into new standards regar- ding supply chain security risks</li> <li>Insights on how these standards influence software driven products in automotive industry</li> <li>Sharing best practices how to miti- gate risks in this context</li> <li>Tobias Löhr, Associate Partner Cyber Security &amp; Digital Compliance, Secu- rity Consulting and Benedikt Bauer, Security &amp; IT Consultant, both of p3 automotive GmbH, Stuttgart</li> </ul>	Electrified Commercial Vehicle Trailers – How to Turn a Conven- tional Trailer into a Hybrid Vehicle - Electrification/hybridisation of heavy duty trailers - Decarbonisation of commercial vehicle transport - eMobility Dr. Nils Pfullmann, Team leader System Solutions Trailer, ZF Fried- richshafen AG, Hannover



09:30	Automotive OS Reloaded – Refocus and Reality Check • The three big promises of the SW defined vehicle – are we on track? • Tectonic shifts: The Automotive Landscape is changing fast • Breaking the Gordian Knot for Scal- able SW Platforms • Imperatives beyond 2023 Dr. DiplPhys. DiplMath. Christof Horn, Head of Automotive Europe Industry X, Industry & Transformation, Accenture, Kronberg	<ul> <li>Validation and Interpretation of Neural Networks: DNN-Based Object</li> <li>Detector as an Example</li> <li>Use-case study and hands-on experience of Al validation</li> <li>Extend Explainable Al to complex ar- chitectures such as an Object Detector</li> <li>A two-stage approach for Al validation and interpretation</li> <li>Al autonomous driving</li> <li>DrIng. XinXing Wang, Team Mana- ger Systems and Sensors Validation, Electronics &amp; Virtual Testing Solutions, Bertrandt Group, subsidiary Ingolstadt and Dr. Khanlian Chung, Product</li> <li>Owner Al Testing, Vector Informatik GmbH, Karlsruhe</li> </ul>	<ul> <li>Master Algorithm for Event-based Co-Simulation with FMI 3.0 for Timing Accurate Software- in-the-Loop</li> <li>Master Algorithm for discrete event driven co-simulation</li> <li>Simulation of FMI 3.0 FMUs with Event mode</li> <li>Clock Based synchronization of FMUs at events</li> <li>Timing Accurate Software-in-the- loop</li> <li>Mythreya Vinnakota, Researcher, Regional Digital Technologies, Bosch Global Software Technologies PVT LTD, Bengaluru, India, Co-authors: Dr. Oliver Kotte, Dr. Laura Beermann, Robert Bosch GmbH, Renningen</li> </ul>	<ul> <li>Tales from an Automotive Penetration Testing Team</li> <li>Automotive Cyber Security</li> <li>ECU Zero-day vulnerabilities</li> <li>Security aware automotive development</li> <li>Itay Lidovski, Security Researcher, Consulting and Research, Co-author: Amit Geynis, both of Argus Cyber Security, Ramat-Gan, Israel</li> </ul>	AWARD project • Project presentation • Hub to hub use case • Forklift use case • Port use case Julien Collier, M. Sc., Project Manager, System, Easy Mile, Toulouse, France
10:00	MB.OS – Our Chip-to-Cloud Architecture • Why designing an own architecture • Mercedes-Benz Operating System – so • Global footprint and continuous integr • Outlook – what's next Magnus Östberg, Chief Software Office	eparation of software and hardware	Development, Mercedes-Benz AG, Sindel	lfingen	
		bit Experience ity with Cloud and EDGE ienior Vice President, Cockpit, Mobile and	Apps, Stellantis, Auburn Hills, MI, USA		
▶ 11:00	Coffee break, Exhibition and Start-up	Area visit		-	
	Panel Discussion	Software – Cloud & Data Moderation: DiplIng. Stefan Singer	System Engineering and Processes Moderation: DrIng. Dieter Rödder, Robert Bosch, Stuttgart	Security – Challenges Moderation: DiplIng. Henning Harbs, Volkswagen AG, Wolfsburg	Components, Subsystems & Integration Moderation: Dr. Falk Hecker, Knorr-Bremse Systeme fuer Nutz- fahrzeuge GmbH, Schwieberdingen
11:45	<ul> <li>A Leap in Innovation? - What European OEMs Can Learn from Chinese OEMs in Terms of User Experience</li> <li>History of Chinese OEM brands and their arrival on the European market</li> <li>Development and latest advancements of Chinese vehicles</li> <li>What European OEMs can learn from their Chinese counterparts and how Chinese OEMs can succeed in Europe</li> <li>Audrey Matarage, Independent</li> </ul>	Sustainable Software Development for Cloud-Native Vehicles • Standardization of Vehicle APIs cross the Automotive Industry • Creating open Eco Systems like Machines, Devices, Applications and DevOps • Defining the next generation of Zo- nal Architectures to realize the SDV DiplIng. (FH) Martin Bornemann, Vice President, Advanced Technology & Architecture, CTO Office, Co-author:	<ul> <li>Challenges in the Synchronous Development of Software, Hardware and Mechanics for Drive Systems</li> <li>Challenges due to different development processes of software, hardware and mechanics</li> <li>New holistic development process based on systems engineering</li> <li>Future possibilities using Big Data, AI and virtual development methods</li> <li>DrIng. Peter Fietkau, Manager Drive System Electronics, Systems Enginee-</li> </ul>	<ul> <li>Why Trusted Execution Environments are Critical for Automotive Security</li> <li>Introduction to Trusted Execution Environments</li> <li>Common Automotive Use Cases</li> <li>Future Use Cases to support Software Defined Vehicles</li> <li>Andrew Till, B.A., General Manager Secure Platform, Executive Team, Trustonic Limited, Cambridge, United Kingdom</li> </ul>	<ul> <li>Modular High-Power-DCDC-Plat- form for FC-Applications – The sixth Generation Bidirectional DCDC</li> <li>A challenge accepted: steady state and highly dynamic operation at the same time</li> <li>Modular approach for scalability and cost-efficiency</li> <li>Flexible design for a wide range of application and markets</li> <li>DrIng. Bernhard Budaker, Vice President, Product Division PE, BRU-</li> </ul>

## 2nd Congress Day

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12:15	<ul> <li>Panel Discussion: Transformation of Working Environment</li> <li>Panelists:</li> <li>Rui Cordeiro, M. Sc. CEO, Critical TechWorks, Porto, Portugal</li> <li>Sebastian Dörner, Software Enginee- ring Community Advocate, People &amp; Culture, Porsche Digital GmbH, Ludwigsburg</li> <li>Andreas Heim, VP of Design, Pro- cess and Technology Engineering, Automotive Business Group, Flex, Stuttgart</li> <li>Joe Justice, Chair Of The Board Of Directors, Agile Business Institute, Tokyo, Japan</li> <li>Joachim Langenwalter, Senior Vice President Autonomous Driving, Autobrains Al Technologies GmbH,</li> </ul>	Rust for Automotive: A Modern, Memory-Safe and Secure Programming Language • Rust programming language on the rise for automotive and industrial applications • Rust for embedded applications • Rust compiler support for Infineon AURIX: Challenges, solution & benefits DiplIng. Mario Cupelli, CTO, HighTec EDV-Systeme GmbH, Saarbrücken	<ul> <li>A Review of using Artificial Intelligence in Large Projects for Requirements Classification</li> <li>Distributing requirements in large projects to ~30 teams</li> <li>Using state-of-the-art transformer AI models</li> <li>Review of EU regulations and Bosch principles using AI for this purpose</li> <li>DrIng. Lutz Trautmann, Group leader for SW and System Architecture and Requirements Management, Cross-Domain Computing Solutions, Robert Bosch GmbH, Hildesheim and Hamza Ghezali, Master Student, Technical University of Clausthal, Co-authors: Steffen Witke, Robert Bosch GmbH, Hildesheim, Prof. Dr. Steffen Herbold, University of Passau</li> </ul>	<ul> <li>Distributed Development along the Automotive Supply Chain: 8 Insight- ful Recommendations for OEMs and Suppliers to Jointly Implement Cybersecurity</li> <li>Cybersecurity as a new quality di- mension in distributed development in the automotive industry</li> <li>Success factors for cybersecurity on the side of the OEM and for Tier-N- Suppliers</li> <li>Requirements for compliance with UN Regulation No 155 and applica- tion of ISO/SAE 21434</li> <li>Best practices and reliable tips for collaboration in cybersecurity chal- lenges: Cybersecurity management/ Cybersecurity engineering Manuel Sandler, Partner, Consulting, CYRES Consulting Services GmbH, Munich</li> </ul>	<ul> <li>The Challenges to Move to Fail-Safe Operation in E/E Architecture</li> <li>Specific challenges regarding fault-tolerant power-net architectu- res in commercial vehicles</li> <li>Comparison with redundancies in already existing systems in com- mercial vehicles (in particular brake systems) and in aviation</li> <li>Concept of a fail tolerant, ASIL capable and modular power-net architecture for commercial vehicles</li> <li>David Kiss, Product Owner, R&amp;D, Knorr-Bremse SfN GmbH, Budapest, Hungary</li> </ul>
12:45	Autobrains Al Technologies GmbH, Berlin Martin Schleicher, Head of Software Strategy, Continental AG, Erlangen	<ul> <li>Software Defined Vehicle: Combining Real-Time Safety Critical Functions with Cloud Connectivity</li> <li>The importance of the right choice of RTOS and middleware for Soft- ware Defined Vehicles</li> <li>Possible ways of consolidating vehicle safety critical and cloud connected applications</li> <li>Managing complexity and perfor- mance in a heterogeneous software architecture</li> <li>Outlook on central computer archi- tectures and cloud native automoti- ve development</li> <li>Nikola Velinov, Senior Business</li> <li>Development Engineer, Green Hills Software LLC, Santa Barbara, CA, USA and Sreeja KS, Senior Architect, Transportation Business Unit, Co-au- thor: Jyotsana Singh, both of Tata Elxsi Ltd., Trivandrum/Bangalore, India</li> </ul>	Addressing the Challenge of 'In- tegrating Everything' – Creating a Blueprint for Automotive Integrated Development Integrate standards, regulations, and different domains Holistic approach how to master complexity To manage work product and product maturity Challenges of integrating "everything" Christian Hübscher, Principal Consul- tant and Ralf Geppert, Consultant, both of Kugler Maag Cie GmbH by UL Solutions, Kornwestheim	<ul> <li>Where is Everybody? Looking for Remote Attacks on Cars in the Wild</li> <li>Honeypot application in the automotive domain</li> <li>Systems that an automotive honeypot should mimic</li> <li>Existing open-source tools that can be used to build an automotive honeypot</li> <li>Niclas Ilg, M. Sc., PhD Student, Corporate Research – Reliable Distributed Systems, Co-authors: Dr. Paul Duplys, Dr. Dominik Sisejkovic, all of Robert Bosch GmbH, Renningen/ Ludwigsburg/Hildesheim</li> </ul>	<ul> <li>Enabling a Software Platform for Faster-feature Deployment in Next-generation Commercial Vehicles</li> <li>How to migrate existing functions to HPC environments</li> <li>How to increase significant reuse of existing legacy software and systems</li> <li>How to create hybrid functions that include service and signal driven designs</li> <li>How to speed-up integration activi- ties for such functions</li> <li>Omkar Panse, Vice President, Head of Middleware Solutions, KPIT Tech- nologies Ltd., Pune, India and Nico Hartmann, CTO, Qorix, Munich</li> </ul>
13:15	Lunch break, Exhibition and Start-up A	Area visit			





16:15 End of the Congress



## **VDI-Workshop**

#### Friday, October 20, 2023

## Power Electronics and Circuit Board Design for E-Mobility – The Latest Megatrends Without Ignoring the Enablers or the Classic Topics

In modern vehicles, power electronics are becoming increasingly important due to electro-mobility and the increasing number of electronically controlled functions. An important component of power electronics are printed circuit boards. Various electronic components are connected to each other on these, allowing them to communicate with each other. The demands on printed circuit boards are also increasing rapidly – higher currents and low volumes bring with them a conflict of objectives that developers must meet.

In this workshop you will first receive a practice-oriented overview of the energy storage devices, switching elements and basic circuits of the power electronics used in modern vehicles. These are presented using practical examples. Furthermore the challenges in the layout and design of printed circuit boards for automotive applications will be discussed. In addition to larger currents and the associated higher temperatures, e.g. an EMC-compliant design and thermal management must be taken into account. You will learn which materials and assemblies are suitable for use in electric vehicles. You will get an overview of the advantages and disadvantages of the various offers on the market and be able to take them into account when designing printed circuit boards.

#### Who is the target group of this workshop?

- Development Engineers
- Project managers
- Technical executives

in the vehicle and supplier industry and at development service providers in the E/E sector

#### Content of this workshop

- Energy storage, consumers, systems, the need for voltage transformation
- Basics HV and the voltage transformation
- Basic voltage transformation circuits
- Interference suppression, mains filter, XY-capacitors, mains filter structure
- Requirements for interference suppression capacitors (DIN EN)
- Components (power transistor, diodes, relays)
- Electronics design process of a circuit board and assembly
- Circuit board manufacturing



#### Date and venue: October 20, 2023 Dorint Hotel Venusberg, Bonn, Germany

Time: 09:00 - 16:30

Workshop Chair: Andreas Wirtz, blue square consulting UG, Cologne

The workshop will be held in German language and with German documentation – no translation!

Register at: www.vdi-wissensforum.de/01ST158



## List of Exhibitors (June 13, 2023)

3D Mapping Solutions GmbH ANavS Sensor Technologies GmbH Apex.Al GmbH APL Automobil-Prüftechnik Landau GmbH **ARM** Limited Aurora Labs AVL List GmbH Bertrandt AG Brose Fahrzeugteile SE & CO. KG, Bamberg Cadence Design Systems GmbH Continental Engineering Services GmbH CTAG Deep Safety GmbH Digitalwerk GmbH dSPACE GmbH EDAG Engineering GmbH Elexir AG Elmos Semiconductor SE EPICNPOC SAS ETAS GmbH FERCHAU Automotive GmbH FEV Europe GmbH Fraunhofer Institute for Integrated Circuits IIS GLIWA embedded systems GmbH & Co. KG GMV Göpel electronic GmbH Green Hills Software GmbH Hamamatsu Photonics Deutschland GmbH Hella GmbH & Co. KGaA HighTec EDV-Systeme GmbH Infineon Technologies AG Inova Semiconductors GmbH IPG Automotive GmbH KIT Karlsruher Institut für Technologie Kitagawa GmbH KooSys GmbH **KPIT** Technologies GmbH Kugler Maag CIE by UL Solutions Magna Steyr Fahrzeugtechnik GmbH & Co. KG MathWorks

MD Elektronik GmbH Microchip Technology MicroNova AG National Instruments Corporation **OPAL-RT Germany GmbH** Dr. Ing. h.c. F. Porsche AG Porsche Digital GmbH Prisma Sales Service GmbH OualiTau Inc. Renesas Electronics Europe GmbH Scantinel Photonics Silicon Mobility STAR COOPERATION STMicroelectronics International NV Swissbit AG TASKING Germany GmbH Tata Technologies GmbH TDK Corporation TDK Europe GmbH TDK-Micronas GmbH Tracetronic GmbH TRUSTONIC Vector Informatik GmbH Volkswagen AG XKrug GmbH

### Exhibition & Sponsorship

We connect you – and your company Would you like to present your products and services to the industry's key players? Participate in the event as an exhibitor or sponsor.

If you are interested, get in touch with: Martina Slominski Team Leader Exhibition & Sponsorship Phone: +49 211 6214-385 E-Mail: slominski@vdi.de

### Start-up Area



ELIV offers young companies the opportunity of presenting their latest developments and products in automotive electronics in the start-up area. Get the chance to meet the exclusive, international group of participants consisting of decision-makers and specialists from vehicle manufacturers, suppliers, and service providers as well as representatives from universities! In addition to a full-service package with a 4 sqm booth space in the start-up area, a presentation slot on the start-up stage is also included.

#### Interested in taking part?

To apply, request the registration documents for the Start-up Area. We are happy to provide assistance and further information:

Jasmin Habel Project Consultant Exhibition & Sponsorship Phone: +49 211 6214-213 Mail: jasmin.habel@vdi.de

The program of the start-up stage is expected to be published in mid-August. You can look forward to exciting presentations. More info at: www.eliv-congress.com/exhibition-and-sponsoring/start-ups/

#### See who is already participating in the start-up area:

ANavS Sensor Technologies GmbH | Deep Safety GmbH | Elexir AG | EPICNPOC SAS | KooSys GmbH | Scantinel Photonics

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# **dSPACE**

dSPACE is a leading provider of simulation and validation solutions worldwide for developing connected, autono-

mous, and electrically powered vehicles. Our range of end-to-end solutions is used particularly by automotive manufacturers and their suppliers to test the software and hardware components in their new vehicles, long before a new model is allowed on the road. Our portfolio ranges from end-to-end solutions for simulation and validation to engineering and consulting services as well as support.

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# KPI1

KPIT Technologies is a global partner to the automotive and Mobility ecosystem for making software-defined vehicles a reality. It is a leading inde-

pendent software development and integration partner helping mobility leapfrog towards a clean, smart, and safe future. With 10000+ automobelievers across the globe specializing in embedded software, AI, and digital solutions, KPIT accelerates its clients' implementation of next-generation technologies for the future mobility roadmap. With engineering centers in Europe, the USA, Japan, China, Thailand, and India, KPIT works with leaders in automotive and Mobility and is present where the ecosystem is transforming.

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### ΤΛΤΛ **TATA** TECHNOLOGIES

Tata Technologies GmbH. a subsidiarv of Tata Technologies. is strategically set up to help German OEMs

and Tier 1s conceptualize, develop, and realize better products that are safer, cleaner, and improve the quality of life for all the stakeholders. It leverages our global diverse talent pool of 11000+ innovators spread across 27+ countries, and global best practices to help our customers develop competitive products and win at the marketplace.

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Brose is the fourth-largest family-owned automotive supplier. Every second new car worldwide is equipped with at least one Brose product. The company's intelligent solutions for vehicle access and interiors provide greater comfort and flexibility. Innovative concepts for thermal management increase

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Contact: Brose Fahrzeugteile SE & Co. Kommanditgesellschaft Christoph Maag, Vice President Electronics Brose Group Berliner Ring 1 | 96052 Bamberg Phone: +49 951 7474 4744 | Fax: +49 951 7474 1767 E-Mail: christoph.maag@brose.com Web: www.brose.com

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Steffen Glemser, Senior Director Automotive OEM Strategic Sales, Renesas Electronics Europe GmbH, Düsseldorf



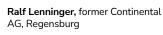
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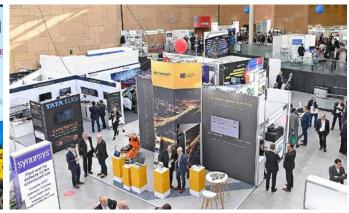
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